

# MET-1601: TECHNICAL STATICS

## Cuyahoga Community College

**Viewing: MET-1601 : Technical Statics**

**Board of Trustees:**

January 2023

**Academic Term:**

Fall 2023

**Subject Code**

MET - Mech Eng/Manuf Ind Eng Tech

**Course Number:**

1601

**Title:**

Technical Statics

**Catalog Description:**

Study of forces on structures and machines at rest. Topics include composition and resolution of forces, moments, freebody diagrams, trusses, frames, simple machines, friction, centers of gravity, centroids, and plane and polar moments of inertia.

**Credit Hour(s):**

3

**Lecture Hour(s):**

3

**Lab Hour(s):**

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## Requisites

**Prerequisite and Corequisite**

MATH-1530 College Algebra; and PHYS-1210 College Physics I, or concurrent enrollment.

## Outcomes

**Course Outcome(s):**

Determine the resultant of concurrent forces in a plane.

**Objective(s):**

1. Use the parallelogram and triangular methods for adding vectors to find their resultants.
2. Apply the method of rectangular components to find the resultant of two or more vectors.

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**Course Outcome(s):**

Apply appropriate calculations to problems to show an understanding of the nature of friction and friction forces.

**Objective(s):**

1. Analyze common mechanical elements such as wedges, bearings, belts whose operations are affected by friction.
2. Solve problems of static equilibrium for which frictional effects must be considered.

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**Course Outcome(s):**

Apply appropriate calculations to problems to show an understanding of centers of gravity and centroids.

**Objective(s):**

1. Solve problems of center of gravity to a variety of mechanical parts.

2. Solve problems of center of gravity for centroids.

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**Course Outcome(s):**

Determine the value of plane moments of inertia.

**Objective(s):**

1. Calculate the rectangular moment of inertia for simple plane areas about centroidal axes.
2. Use the parallel axis theorem to determine rectangular moments of inertia.

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**Course Outcome(s):**

Apply the principles of force vectors to determine force transmission in simple machines.

**Objective(s):**

1. Draw complete free-body diagrams for rigid bodies constrained by various types of supports.
2. Solve for any unknown forces acting on a point of equilibrium.
3. Compute the moment of a force about any selected point on an object.
4. Write and solve the equations of equilibrium for a rigid body or simple machine acted on by one or more external loads.

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**Course Outcome(s):**

Apply the principles of force vectors to determine loads in members of simple trusses.

**Objective(s):**

1. Use the method of joints to analytically determine the force transmitted in each link of a plane truss and determine whether each link is in tension or compression.
2. Apply the method of rectangular components to find the resultant of two or more vectors.

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**Methods of Evaluation:**

- a. Assignments
- b. Quizzes
- c. Final examination

**Course Content Outline:**

- a. Basic Concepts
  - i. Review of gravitational and SI systems of units
  - ii. Review of trigonometry
  - iii. Technical computations
- b. Resultant of Concurrent Forces in a Plane
  - i. Force vectors
  - ii. Components of a force
  - iii. Resultant of concurrent forces
- c. Equilibrium
  - i. Conditions for equilibrium
  - ii. Free – body diagrams
  - iii. Rectangular components
- d. Resultant of Nonconcurrent Forces in a Plane
  - i. Transmissibility
  - ii. Moment of a force
  - iii. Theorem of moments
  - iv. Couples
  - v. Resultant of distributed loading
- e. Equilibrium of a Rigid Body

- i. Support conditions for bodies in a plane
- ii. Construction of free – body diagrams
- iii. Equations of equilibrium of a rigid body
- f. Force Analysis of Structures and Machines
  - i. Simple plane trusses
  - ii. Method of joints
  - iii. Method of sections
  - iv. Frames and Machines
- g. Friction
  - i. Angle of friction
  - ii. Wedges
  - iii. Square - threaded screws; screw jacks
- h. Center of Gravity, Centroids, and Moments of Inertia
  - i. Center of gravity
  - ii. Centroid of a plane area
  - iii. Moment of inertia of a plane area
  - iv. Parallel axis theorem
  - v. Polar moment of inertia and radius of gyration

## Resources

Bedford, Anthony and Wallace Fowler. *Engineering Mechanics: Statics*. 5th Ed. Upper Saddle River, NJ., 2008.

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Beer, Ferdinand, E. Johnston, John DeWolf, David Mazurek. *Statics and Mechanics of Materials*. 3rd ed. McGraw Hill, 2021.

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Hibbeler, Russell. *Structural Analysis*. 8th Ed. Upper Saddle River, NJ., 2012.

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Hibbeler, Russell. *Statics and Mechanics of Materials*. 3rd Ed. Upper Saddle River, NJ., 2011.

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Hibbeler, Russell C. *Engineering Mechanics: Statics & Dynamics*. 15th. NA: Prentice Hall, 2022.

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Morrow, H.M. and Robert Kokernak. *Statics and Strength of Materials*. 7th Ed. Upper Saddle River, NJ., 2011.

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Limbrunner and Leonard Spiegel. *Applied Statics and Strength of Materials*. Pearson Prentice Hall, 2020.

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Plesha, Michael, Gary Gray, Robert J. Witt, Francesco Costanzo. *Engineering Mechanics: Statics and Dynamics*. 3rd ed. McGraw Hill, 2023.

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## Resources Other

- a. Calculator.
- b. Carnegie Mellon University's Engineering Statics Open Course Textbook <http://oli.cmu.edu/courses/free-open/engineering-statics-course-details/>

## Instructional Services

### OAN Number:

Transfer Assurance Guide OET007

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Key: 2892